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JC932 U.S. PTO

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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant: Norman A. Shoenfeld  
Invention: High Resolution Sheet Metal Scanner

October 18, 2000

COMMISSIONER OF PATENTS AND TRADEMARKS  
WASHINGTON, D.C. 20231 -- BOX PATENT APPLICATION

NEW APPLICATION TRANSMITTAL (SMALL ENTITY)

Sir:

Transmitted herewith for filing is the above-identified patent application of the above-identified inventor.

- (1) Patent application including 7 pages of specification, 11 claims, abstract, and 4 sheets of formal drawing.
- (2) Combined Declaration and Power of Attorney.
- (3) Verified Statement (Declaration) Claiming Small Entity Status.
- (4) An assignment of the invention to S&S X-Ray Products, Inc.
- (5) Check for \$ 395.00, including (a) assignment recordal fee of \$40.00 and (b) application filing fee of \$355.00.

calculated as follows:

	CLAIMS AS FILED	EXCESS OVER BASIC	RATE	FEE
BASIC FEE	---	--	--	\$ 355
TOTAL CLAIMS	11	(Minus 20 =) 0	X \$09 =	\$ 0
INDEP CLAIMS	1	(Minus 3 =) 0	X \$40 =	\$ 0
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- (6) Information Disclosure Statement, including (a) Form PTO-1449 and (b) copy of each reference listed therein.

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PATENT TRADEMARK OFFICE

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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Application of: Norman A. Shoenfeld  
Filed: Concurrently herewith  
For: **High Resolution Sheet Metal Scanner**

Attorney Docket No. 522.008PA

COMMISSIONER OF PATENTS AND TRADEMARKS  
WASHINGTON, D.C. 20231

VERIFIED STATEMENT (DECLARATION) CLAIMING  
SMALL ENTITY STATUS (37 CFR 1.9(f) and 1.27(c))  
SMALL BUSINESS CONCERN

Sir:

I hereby declare that I am president of the following small business concern, and am empowered to act on behalf of said concern: S&S X-Ray Products, Inc., located at 1101 Linwood Street, Brooklyn, NY 11208

I further declare that the above-identified concern qualifies as a small business concern as defined in 13 CFR 121.3-18, and reproduced in 37 CFR 1.9(d), in that the number of employees of the concern, including those of its affiliates, does not exceed 500 persons. For purposes of this statement, (1) the number of employees of the business concern is the average over the previous fiscal year of the concern of the persons employed on a full-time, part-time or temporary basis during each of the pay periods of the fiscal year, and (2) concerns are affiliates of each other when either, directly or indirectly, one concern controls or has the power to control the other, or a third-party or parties controls or has the power to control both.

I hereby declare that rights under contract or law have been conveyed to and remain with the small business concern identified above with regard to the invention entitled: **High Resolution Sheet Metal Scanner** by inventor Norman A. Shoenfeld, and described in the specification filed herewith.


The rights held by the above-identified small business concern in this invention are exclusive. Neither said inventors nor said small business concern has assigned, granted, conveyed or licensed nor is under any obligation under contract or law to assign, grant, convey or license, any rights in the invention to any person who could not be classified as an independent inventor under 37 CFR 1.9(c) if that person had made the invention, or to any concern which would not qualify as a small business concern under 37 CFR 1.9(d) or a nonprofit organization under 37 CFR 1.9(e).

I acknowledge the duty to file, in this application or patent, notification of any change in status resulting in loss of entitlement to small entity status prior to paying, or at the time of paying, the earliest of the issue fee or any maintenance fee due after the date on which status as a small entity is no longer appropriate. (37 CFR 1.28(b)).

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application, any patent issuing thereon, or any patent to which this verified statement is directed.

Norman A. Shoenfeld  
President, S&S X-Ray Products, Inc.

  
Signature

  
Date

## High Resolution Sheet Metal Scanner

### ***Background of the Invention:***

This invention relates to automatic scanning equipment and techniques, and is more particularly directed to a scanner that employs machine vision to check a sheet metal part or the like for accuracy of punched or drilled holes or other structure. The invention is more specifically concerned with a scanner device and technique in which a metal sheet can be scanned and then compared to an existing drawing or blue-print, which can be in CAD or digitized form, for hole locations and tolerances. The invention is also concerned with scanning devices in which the part can be scanned to produce a blue-print or drawing directly, or on which a blue-print can be scanned using machine vision.

In many manufacturing processes it is necessary to assure the accuracy of dimensions of parts and subassemblies prior to further assembly, and this is particularly true for workpieces or parts that are formed of sheet metal, where holes and cutouts must be in precise locations and must be specific sizes and shapes, within very narrow tolerances.

An automated scanning device is used for this purpose, in which the part to be checked is illuminated and a video image is processed to obtain the required measurement data. In many cases, a laser beam or plural laser beams are swept across the part, and the device picks up either light reflected from the part or the light that passes through it. In either case, the laser has to be oriented at an angle to the part for capturing portions that are away from the central axis of the scanning device. This produces distortion in images of apertures or of edges, especially if the part has a finite thickness. Other scanning devices employ a video camera that captures an image of the part, or in some cases is moved in an X,Y pattern. For these purposes, the part is laid upon a light table, and the camera or other imager is positioned above the light table. In these systems, the camera and the movable carriage are exposed to dust and other atmospheric contaminants that one would expect to find associated with any sheet metal manufacturing process.

### ***Objects and Summary of the Invention***

Accordingly, it is an object of the present invention to provide an improved technique for checking a part for accurate location and tolerance, and which avoids the drawbacks of the prior

art.

It is another object to provide a scanner in which any moving parts are contained within an environmentally sealed housing, so that there are no exposed moving parts.

It is a further object to provide a scanning arrangement which can produce scans of higher resolution or at increased scan speeds.

It is still another object to provide a sheet metal scanner which can accurately measure location and tolerance of holes and openings, even where the part is thick.

It is another object to provide a sheet metal scanner which can be adapted for scanning of architectural drawings, blueprints, or the like for conversion into a CAD drawing, a bit-map drawing, or another digital format.

In accordance with an aspect of the present invention, the scanning apparatus is based on a high-resolution, line-scanning camera mounted to an X-Y table, located in a lower assembly having an environmentally sealed housing. On the top of the housing is a transparent support plate, e.g., a sheet of glass 48 inches by 48 inches, upon which the sheet metal part (or blue-print) is placed. The line-scan camera is precision focused on the top surface of the glass support plate. Approximately 18 inches above the glass plate is a fixed light source, i.e., an illuminator, which supplies a uniform bright light to the entire 48 inch by 48 inch viewing field. This can be based upon an array of parallel fluorescent tubes. A polarizing filter placed in front (i.e., above) the camera lens attenuates light that is reflected off the glass. In addition to this, inner surfaces of the sealed lower assembly, as well as the surfaces of the X-Y table, are coated with a non-reflective paint to eliminate light artifacts. In this arrangement, there are no moving parts of the apparatus outside the sealed lower portion, so there is no chance of contamination or failure due to factory dust or other particulates on moving parts or on the camera optics. A positioning device allows fine adjustment of the glass support plate to keep the camera in excellent focus for high resolution scans. Also, damping devices can be incorporated into legs of the unit to accommodate for shocks and vibrations. These may be in the form of rubber-based air or oil-filled dampers, and may be tuned to cancel out specific common vibration frequencies on the factory floor.

The X-Y table may be of the type in which there are X- and Y- precision rails, as well as associated lead screws and stepper motors, or timing belts and pulleys and stepper motors, plus motor controllers and encoders such as high-resolution tape encoders, permitting high resolution camera movement (e.g., 0.002 inch resolution or better). The size of the scan undertaken by the X-Y table can be controlled to match the size of the part, where the part is smaller than the full 48 by 48 inches, so as to carry out the scan in a reduced time.

A computer control may be used for controlling the camera and the X-Y table. Software, which may be compatible with Windows NT or Windows 2000, constructs the two-dimensional image of the part from line scans, and may import an existing CAD drawing file for comparison. The CAD file may be in \*.DXF or \*.DWG format. The software then compares the scan to the drawing. The software compares features on the scanned part to specific features on the drawing, and produces a report regarding which items fall within acceptable tolerance, and which do not. The software may also reverse-engineer a part, creating a \*.DXF file or the like based on the scan. The software is also capable of piecing together multiple scans, where an object is greater than 48 inches in length, for example, or may also perform scans of multiple objects placed at the same time on the top surface of the support plate. In the latter case, each object is compared individually with a respective drawing.

The above and many other objects, features, and advantages of this invention will become apparent from the ensuing description of a selected preferred embodiment, which is to be considered in connection with the accompanying Drawing.

### ***Brief Description of the Drawing***

Fig. 1 is a side elevation of a high-resolution sheet metal scanner according to one embodiment of this invention.

Fig. 2 is a front elevation of this embodiment.

Fig. 3 is a plan view of the lower assembly of this embodiment, taken at 3-3 of Fig. 2.

Fig. 4 is a schematic view of this embodiment.

Fig. 5 is a plot of a scan pattern of this embodiment.

***Detailed Description of the Preferred Embodiment***

With reference to the Drawing, and initially to Figs. 1 to 3, a high-resolution scanner arrangement 10 has a lower assembly 11 that is environmentally sealed within a housing 12, with all the moving parts and all the sensitive optics contained within this sealed housing 12. A horizontal flat glass plate 13, here with a width and breadth of 48 inches by 48 inches, is fitted into a top wall of the lower assembly 11 and serves as a support plate on which the sheet metal part is laid for checking. A two-stage X-Y table or plotter 14 is situated within the lower assembly housing 13, and has a movable carriage 15 on which a high-resolution line-scan camera 16 is mounted. The camera 16 has its optic axis oriented vertically, and has a focussing lens group 17, and a polarizing filter 18 situated above, i.e., in advance of the lens group 17. The polarizing filter serves to attenuate any stray light that may be, e.g., reflected from the interior surfaces of the lower assembly. Details of the X-Y table 14 will be discussed in more detail later. The interior surfaces of the housing 12, and the surfaces of the X-Y table and other internal elements, are preferably coated with a non-reflective paint, which also minimizes any internal reflections.

The lower assembly 11 is mounted on a frame 19, in which there are support legs 20.

An upper assembly 21 is supported on the frame 19 directly above the lower assembly 11, and comprises a flat illuminator panel 22, which serves as a source of uniform bright white light, and which is coextensive with the 48 inch by 48 inch support plate 13. As shown, the illuminator panel 22 has a number of parallel fluorescent tubes 23, with a reflector 24 above them and a diffuser plate 25 beneath. The diffuser plate 25 may be frosted glass. In this embodiment, the upper assembly 21 is positioned about eighteen inches above the glass support plate 13, although in other embodiments this distance could be greater or less. The illuminator panel 22 is an extremely bright, uniform light source, utilizing high frequency electronic ballasts for the fluorescent tubes 23.

As also shown in Figs. 1 and 2, there are oil-filled vibration dampers 26 fitted on the legs 20, respectively. These may be adjusted to absorb vibrations at specific frequencies, so as to compensate for vibrations found at the factory floor where the scanner 10 is in use. Other types

of vibration dampers and compensators could be employed, including rubber-based, or air-filled. These may be tuned by adjusting the pressure or fill. This feature makes the scanner more resistant to normal movement on the factory floor, whereas existing scanners experience difficulties in function or in accuracy, due to shaking and vibrations, when placed in a factory environment. As also shown in Fig. 1, there may be adjustment screws 27 for fine adjustment of the position of the glass support plate 13, such that the image formed by the camera 16 is in sharp focus on the upper surface of the plate 13. This keeps the camera 16 in fine focus for high-resolution scans.

Details of the X-Y table 14 are shown in Fig. 3, with additional reference to the schematic view of Fig. 4. In this embodiment the table 14 has a pair of first-stage precision rails 30 and 31 that are oriented in the fore-and-aft direction or Y direction. A pair of second-stage precision rails 32 and 33 are movably supported on the rails 30, 31 and these rails 32 are oriented in the orthogonal, i.e., right-to-left or X direction. The carriage 15 is supported on the second stage rails 32, 33. A first stage lead screw 34 is mounted in the housing 12 parallel with the rails 30, 31 and is controllably rotated by a first stage stepper motor 35 to control the position of the second stage rails 32, 33. A second stage lead screw 36 is supported on the rails 33, 34 and parallel with them and is controllably rotated by a second stage stepper motor 37 to control the position of the carriage 15 in the X direction. As shown here, there are first and second stage index ribbons or tape encoders 38 and 39 for sensing the position of the table in the Y and X directions, respectively.

All of the moving parts of the X-Y table 14 are contained within the housing 12 and are protected against dust, moisture, and contaminants. The optical elements, i.e., the camera 16, lens group 17 and filter 18, are also environmentally sealed within the lower assembly and thus are also protected from dust and other environmental sources of degradation.

Moreover, in this system, with the camera 16 being vertically oriented and scanned in the X and Y directions against the uniform light of the illuminator panel 22, the sheet metal scanner can measure hole positions and dimensions accurately, even for deep, narrow apertures in thick workpieces. The scanning action of this arrangement avoids problems due to parallax, and

avoids the elliptical distortion of openings that occurs off-axis with standard camera imaging, especially for parts and workpieces of significant thickness.

As shown in Fig. 4, in association with the tape encoders, 38, 39, lead screws 34, 36, and stepper motors 35, 37, controller 40 is provided to control the position of the carriage 15 in the X and Y directions. The controller 40 can be a microprocessor board with leads connecting to the stepper motors 35, and 37, as well as to the encoders 38 and 39. The controller 40 may also include video processing circuitry for storing and/or processing raw lines of video from the camera 16 that is mounted on the X-Y carriage 15. A standard computer cable 41 can link the controller 40 with a computer or PC 42. In the preferred embodiment, the computer 42 has a Windows NT or Windows 2000 operating system, but the invention is not limited to any specific operating system. In other embodiments, the host computer could be a Macintosh or another system.

As shown in Fig. 5, the X-Y carriage 15 and camera 16 move in a back and forth raster pattern, moving across the scanner in the Y direction, and then moving an increment in the X direction before moving back across in the Y direction. In this case, the line of pixels 43 that is picked up by the camera 16 is oriented horizontally across the scanning or Y direction. There may be some overlap in the scanning from one increment in the X direction to the next. The software used in the computer 42 builds a two-dimensional image based on the pixel lines 43, so that the complete two-dimensional image is accurate to a resolution of 0.002 inches. Of course, it is possible to employ a faster scan if less resolution is needed. The software also makes it possible to piece together multiple partial images, for example, if the part or workpiece has a dimension of more than 48 inches. In addition, if the workpiece is relatively small, i.e., occupying only a fraction of the entire 48 inch square available, then the X-Y table is controlled so as to scan only that portion occupied by the workpiece. The scan size can be entered in terms of X and Y coordinates to match the part size. This produces a faster scan without any loss of resolution.

The associated software can reconstruct a two-dimensional image from the line scans, and can also import an existing CAD drawing file (typically, either in a \*.DFX or in a \*.DWG



format). The software also compares features on the scan to specific features on the drawing, and produces a report regarding which items fall within acceptable tolerance, and which do not. The software can also reverse-engineer a part or workpiece, and can produce a \*.DFX file from the scan. This information can be used for producing a blueprint, or for calibrating a machine tool or correcting a calibration. The software permits multiple scans to be pieced together for measuring large objects, and also permits multiple objects all to be placed on the scanning surface of the plate 13 for simultaneous scanning. The objects can later be individually selected from the completed scanned image. The scanned information can also be shared, using network capabilities of the computer 42 and software.

With the illustrated embodiment, it is possible to scan the 48 inch by 48 inch surface at a resolution of 0.002 inches or better, and it is possible to achieve a scan at a resolution above 0.002 inches in less than two minutes. The scanner 10 can scan objects of several inches in thickness, without compromising measurements of aperture size or location.

An embodiment that uses an X-Y plotter 114 with timing belt drives instead of lead screws is illustrated schematically in Fig. 6, where similar elements to those shown in Fig. 4 are identified with the same reference numbers. Here, there is a Y-direction drive formed of stepper motor 135, timing belt 134 and pulley 140, and an X-direction drive formed of stepper motor 137, timing belt 136 and pulley 141. The carriage 15, as well as the precision rails and other elements function as described previously.

While the invention has been described hereinabove with reference to a selected preferred embodiment, it should be recognized that the invention is not limited to that precise embodiment. Rather, many modification and variations would present themselves to persons skilled in the art without departing from the scope and spirit of this invention, as defined in the appended claims.

*I Claim:*

1 1. High-resolution sheet metal scanner using machine vision for checking the accuracy of  
 2 openings drilled or punched into a mechanical part, comprising:

3 a lower assembly which includes a housing which is environmentally sealed sufficiently  
 4 to exclude dust and contaminants; a planar scanning carriage assembly within said housing and  
 5 capable of producing controlled movement of a carriage member in two orthogonal directions in  
 6 a horizontal plane; a flat transparent support plate disposed on an upper side of said housing on  
 7 which said part is to be supported for viewing; and a camera assembly mounted on said carriage  
 8 member and oriented upwards including an imager for producing at least one line of pixels and  
 9 focussing means for focussing said imager upon an upper surface of said support plate;

10 a planar illuminator mounted above said lower assembly and providing a substantially  
 11 uniform light over an area coextensive with said support plate; and

12 control means coupled with said carriage assembly and with said camera assembly for  
 13 guiding said camera assembly in a controlled scanning pattern within said lower assembly  
 14 housing and processing image data of said part based on lines of pixels produced by said camera  
 15 assembly imager.

1 2. The high-resolution sheet metal scanner of Claim 1 wherein said camera assembly includes a  
 2 polarizing filter.

1 3. The high-resolution sheet metal scanner of Claim 1 wherein said illuminator includes a bank  
 2 of parallel fluorescent tubes.

1 4. The high-resolution sheet metal scanner of Claim 1 wherein said scanning carriage assembly  
 2 includes a first lead screw, a first stepper motor for controllably rotating said first lead screw, a  
 3 second lead screw, a second stepper motor for controllably rotating the second lead screw, first  
 4 and second stage rails arranged orthogonally and means for permitting said carriage to travel

5 along said first and second stage rails in accordance with rotation of said first and second lead  
6 screws.

1 5. The high-resolution sheet metal scanner of Claim 4 including first and second high-resolution  
2 tape encoders within said housing for determining X and Y location of said carriage.

1 6. The high-resolution sheet metal scanner of Claim 1 wherein said imager includes a linear  
2 imager producing one line of pixels at a time.

1 7. The high-resolution sheet metal scanner of Claim 1 including position adjusting means for fine  
2 adjustment of vertical position of said support plate.

1 8. The high-resolution sheet metal scanner of Claim 1 wherein said control means includes  
2 means to adjust the dimensions of scan to the size of the part.

1 9. The high-resolution sheet metal scanner of Claim 1 wherein said lower assembly further  
2 includes motion damping support means to minimize effects of floor vibration on action of the  
3 scanning carriage assembly.

1 10. The high-resolution sheet metal scanner of Claim 9, wherein said motion damping means  
2 includes means for tuning to damp out specific frequencies.

1 11. The high-resolution sheet metal scanner of Claim 1, wherein said scanning carriage assembly  
2 includes respective first and second timing belts and pulleys acting in first and second orthogonal  
3 directions, first and second stepper motors operatively coupled to the first and second timing  
4 belts, respectively, first and second-stage rails arranged orthogonally and means for permitting  
5 said carriage to travel along said first and second stage rails in accordance with rotation of said  
6 first and second timing belts.

***Abstract***

1           A high resolution sheet metal scanner employs machine vision to check a sheet metal part  
2   or the like for accuracy of punched or drilled holes or other structure. A high-resolution line-  
3   scanning camera mounted to an X-Y table, located in an environmentally sealed lower assembly.  
4   The sheet metal part is placed upon a transparent support plate atop of the lower assembly. The  
5   line-scan camera is precision focused on the top surface of the glass support plate. A fixed light  
6   source, i.e., illuminator, is situated above the glass plate, and supplies a uniform bright light to  
7   the entire viewing field. The camera is transported in the X and Y directions on a carriage of the  
8   X-Y table. Damping devices can be incorporated into legs of the unit to accommodate for shocks  
9   and vibrations. A computer control may be used for controlling the camera and the X-Y table.  
10   Software in the computer constructs the two-dimensional image of the part from line scans, and  
11   may import an existing CAD drawing file for comparison.

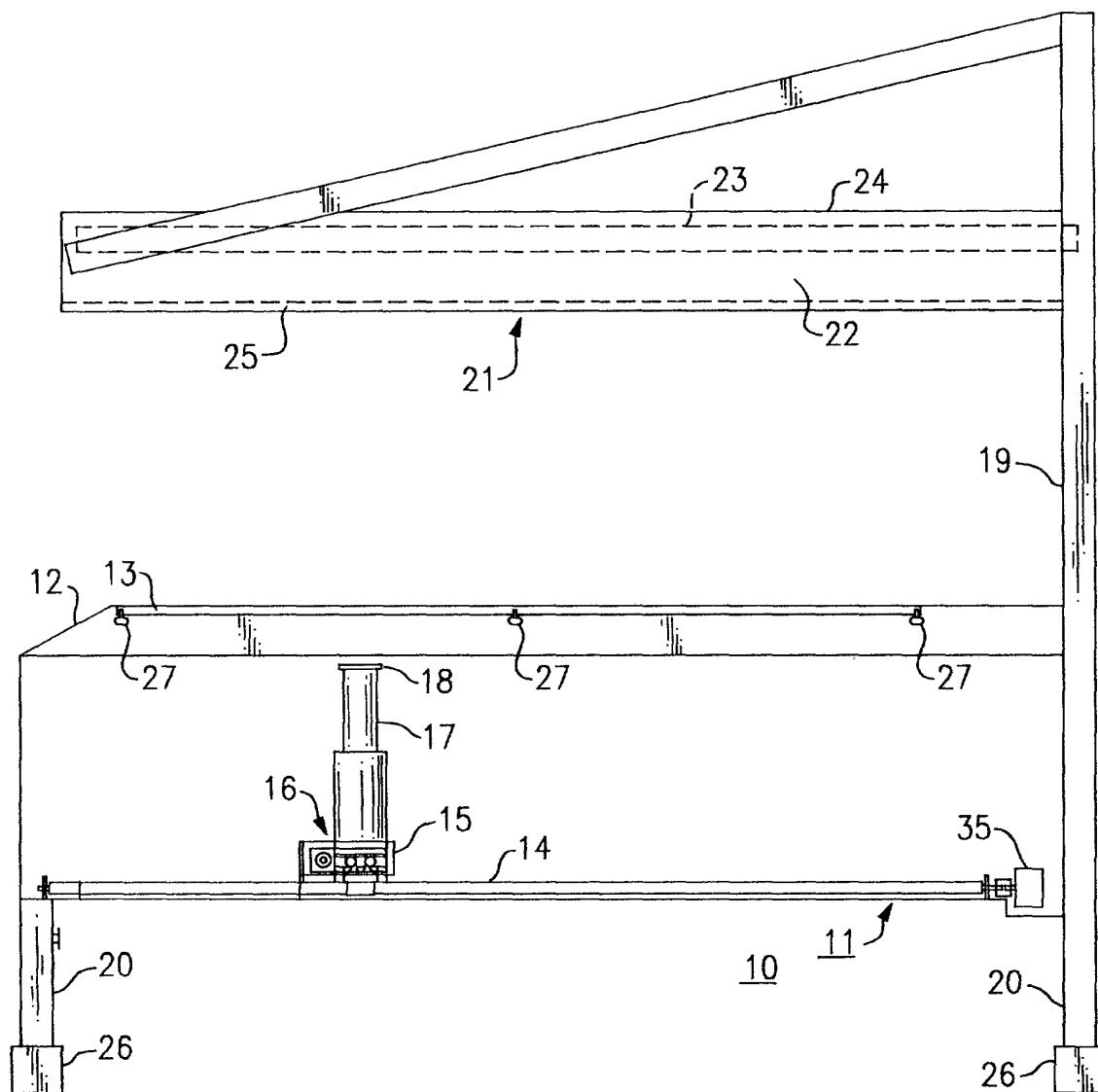
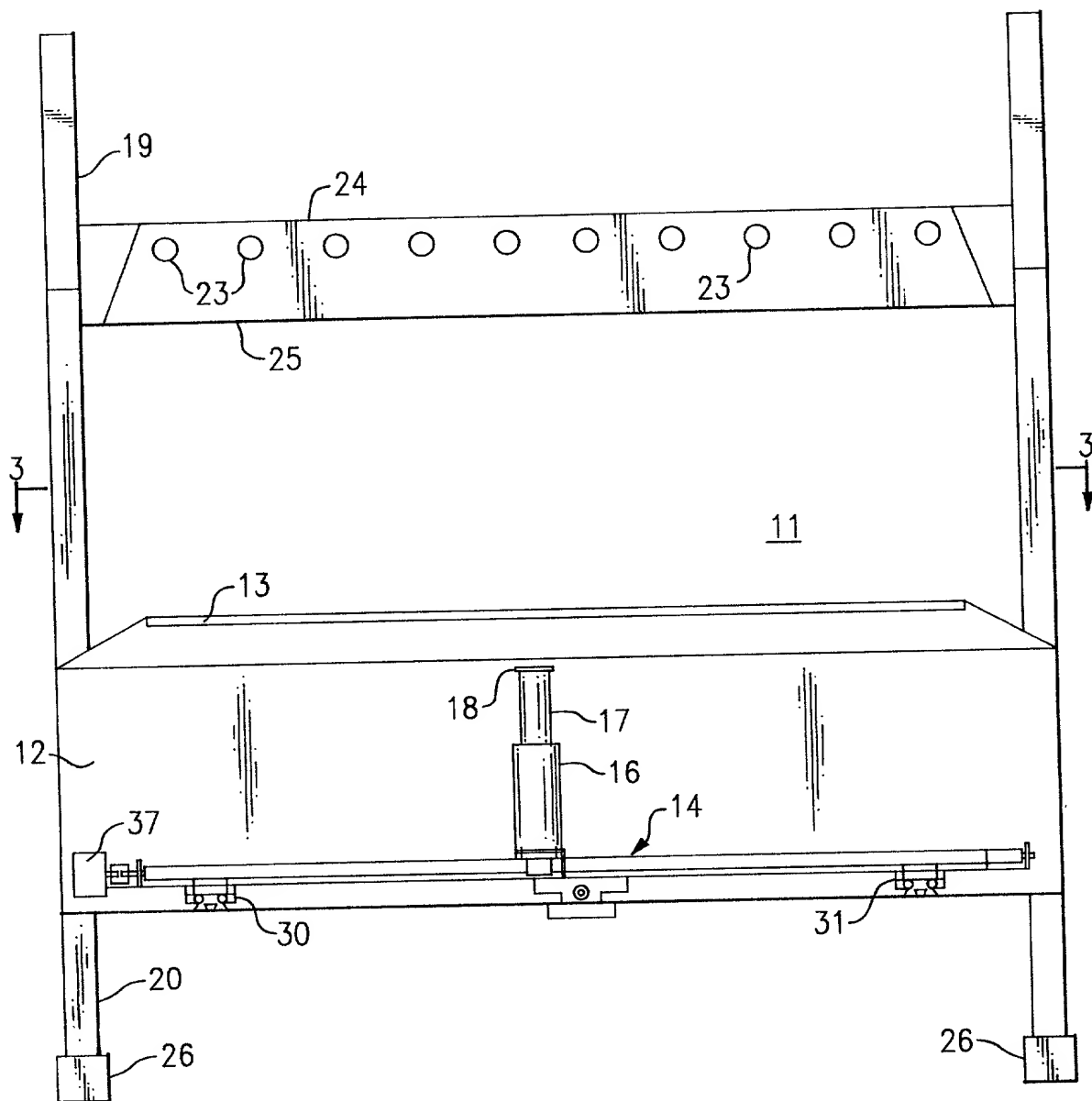
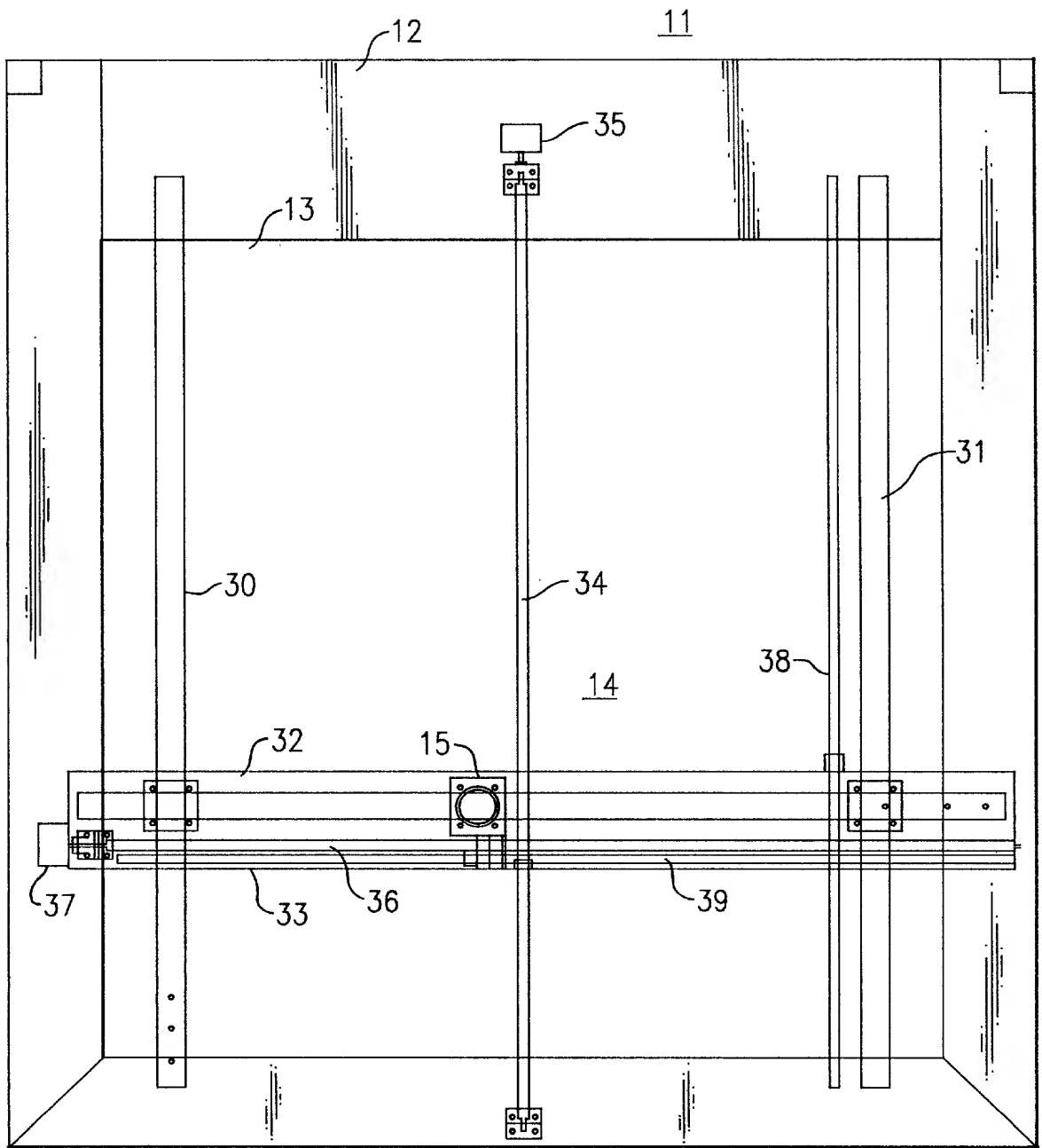
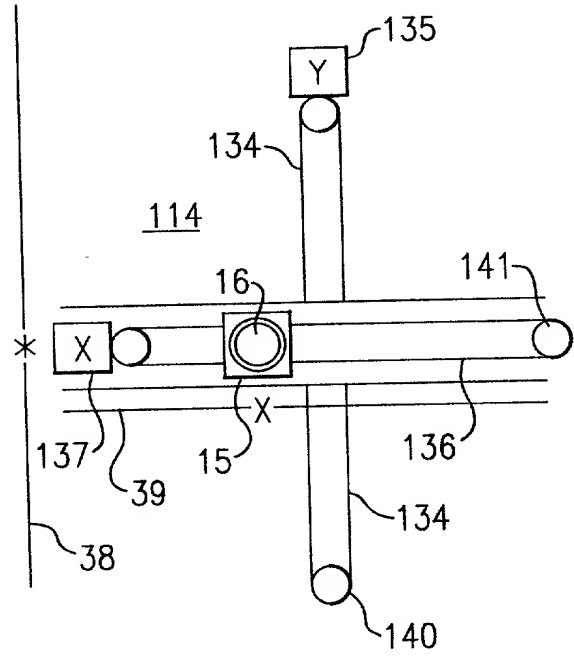
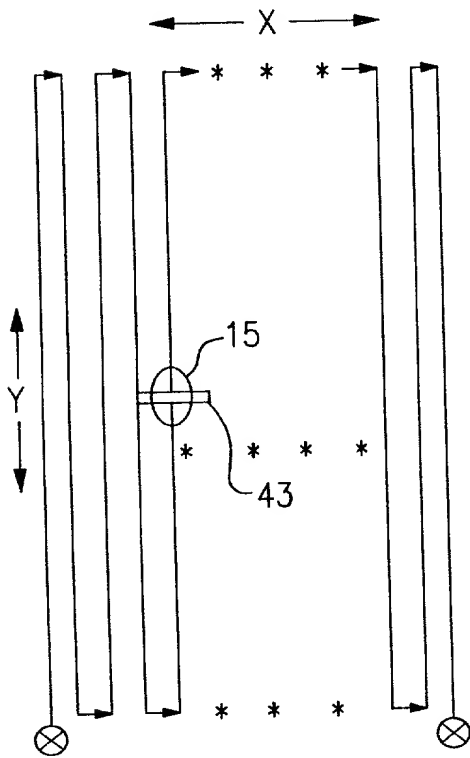
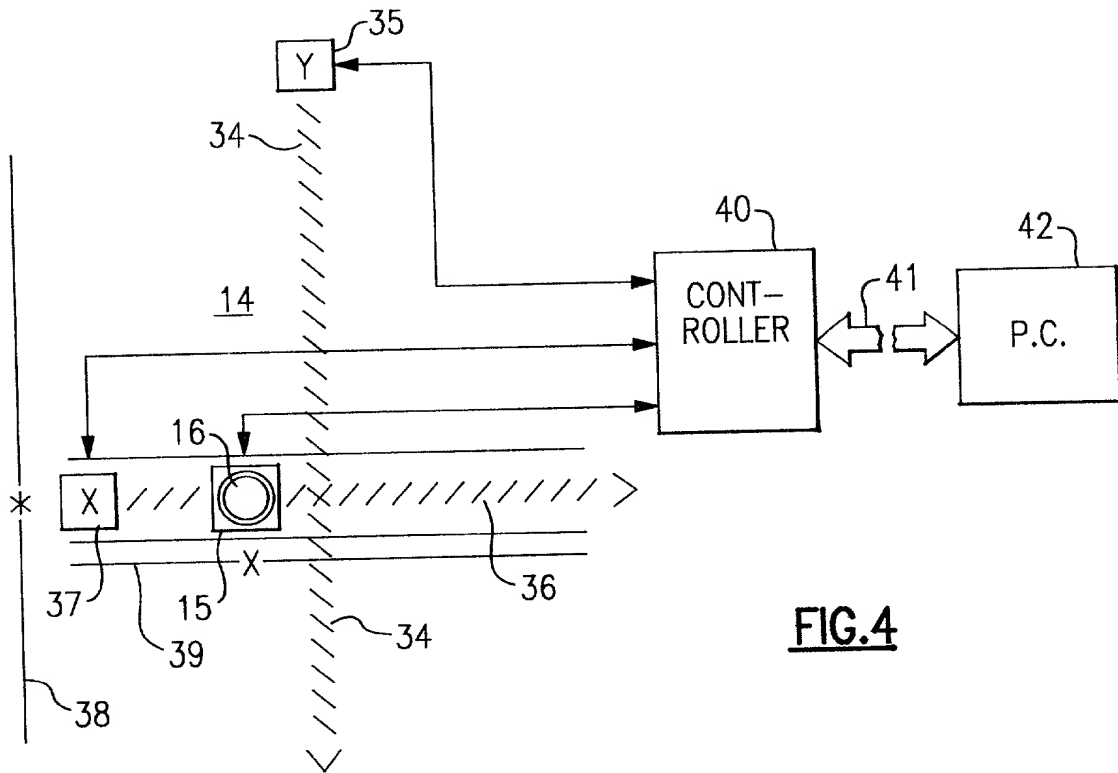


FIG.1

**FIG. 2**



**FIG.3**





## **DECLARATION AND POWER OF ATTORNEY FOR PATENT APPLICATION**

My residence, post office address and citizenship are as stated below next to my name;

I believe I am an original, first and sole inventor of the subject matter which is claimed and for which a patent is sought on the invention entitled **High Resolution Sheet Metal Scanner** the specification of which is attached hereto.

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, Code of Federal Regulations, Sec. 1.56(a).

I hereby claim priority benefits under Title 35, United States Code, Sec. 119(a) to (d) of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any material foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed: **NONE**

Priority Claimed

No

I hereby claim priority benefit under Title 35, United States Code, Sec. 119(e) of any provisional application(s) as identified below: **NONE**

(Date Filed)

I hereby claim the benefit under Title 35, United States Code, Sec. 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code, Sec. 112, I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, Sec. 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application:  
**NONE**

**POWER OF ATTORNEY:** As a named inventor, I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and transact all business in the Patent and Trademark Office connected therewith.

Bernhard P. Molldrem, Jr. Reg. No. 28,973:

**Direct Telephone Calls to:**

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TEL (315) 422-4323  
FAX (315) 422-4318

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full name of sole inventor Norman A. Shoenfeld

Date \_\_\_\_\_

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